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USER MANUAL PCDI-10K PROGRAMMABLE CDI IGNITION AND PV CONTROLLER

TECHNICAL DATA

Limit values:

- minimum revs	200 RPM
- maximum revs	20000 RPM
- minimum supply voltage	8 Volts
- maximum supply voltage	16 Volts
- max. supply voltage for 1 minute	35 Volts
- current draw	25 mAmp
- maximum continuous current for shift light output	1 Amp
- peak current for shift light output	5 Amp

Circuit is protected against reverse supply voltage (wrong connection).

Features:

- CDI charged from hi voltage charging coils (generator)
- store and load function for 2 ignition maps
- one input for magnetic pickup
- external switch for changing ignition map while riding
- shift light output
- quick shift (shift kill)
- tachometer output
- advance/retard whole ignition curve
- three stage rev limit (retard timing, reduced spark, spark off)
- signal delay compensation
- timing calculation for every 1 RPM change (1000, 1002, .. , 9805, 9806, ...)
- programmable power valve actuation
- programmable max close and max open positions
- self PV test on power-up
- PV error detecting (position sensor failure, servo motor failure)
- easy and fast programming on the field, via hand held programmer
- programming while machine running - you can immediately see effects
- monitoring of rev's, ignition and PV angle, via LCD(hand held programmer)
- fast processing for high accuracy - delays from 1us

1. HOW TO ENTER MENU

PCDI must be connected to power supply. Connect **programmer** to **PCDI** and wait few seconds for activation of **programmer** and then press . With pressing or you can move through menu and select with pressing .

Exit menu with selecting *Exit*.

2. MENU ORGANISATION

Set Ign. - set ignition parameters submenu
Set PV - set PV parameters submenu
Exit

2.1. SET IGNITION PARAMETERS SUBMENU

Load Ign. Curve - load previously saved ignition curve set (from #1 to #2)
Save Ign. Curve - save new ignition curve set (from #1 to #2)
Ignition Curve - ignition curve parameters submenu
Advance - advance/retard whole ignition curve
Shift Light - shift light
Shift Kill Time - shift kill time
Rev Limit - rev limit
Static Angle - static angle (stator position)
Compensation - signal delay compensation (from pickup to spark plug)
Remote SW - activating/deactivating external switch
Exit

2.2. SET PV PARAMETERS SUBMENU

Open Rev Point - open rev point
Close Rev Point - close rev point
Close Position - max close valve position
Open Position - max open valve position
PV test - valve position test
Power-up Test - enable/disable power-up test
Exit

3. LOAD IGN. CURVE

Enter menu and move to *Load Ign. Curve* with pressing or and then press .
Now you can select position number of previously saved ignition curve set, with pressing or and then press .

4. SAVE IGN. CURVE

Enter menu and move to *Save Ign. Curve* with pressing or and then press .
Now you can select position number to which you want to save your ignition curve set, with pressing or and then press .

5. Change IGNITION CURVE

Enter menu and move to *Ignition Curve* with pressing or and then press .
Now you are in submenu for setting ignition curve.

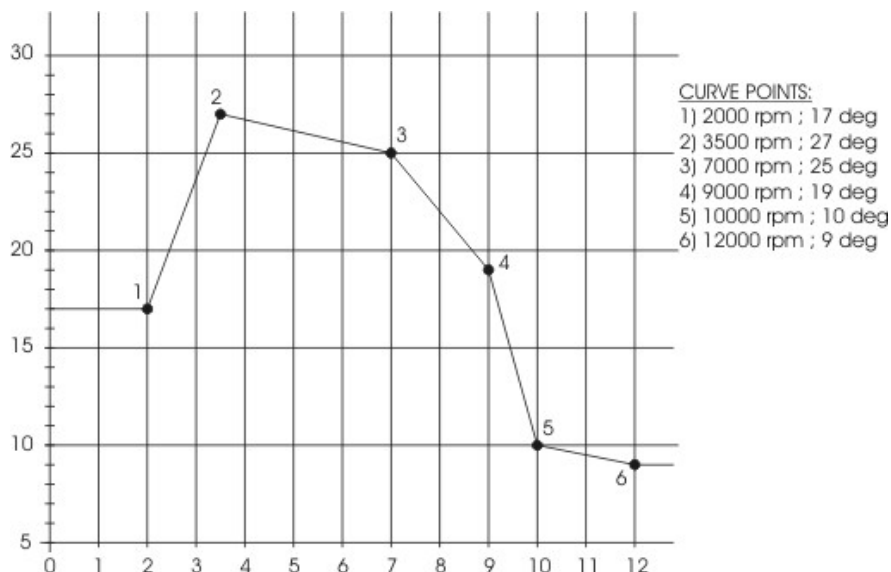
Submenu organisation:

- Nr. of Points** - number of ignition curve points (from 4 to 10)
- 1)** - first ignition curve point
- 2)** - second ignition curve point
- ...
- ...
- Exit Curve** - exit submenu

Important!

To avoid wrong processing, don't make unreasonable curve course.
Every time you make any changes to ignition curve, it is automatically saved to #0 position.
Then you can save it to any other position number from #1 to #2.

Curve Example with six curve points:



5.1. Change NUMBER OF IGNITION CURVE POINTS

Move to *Nr. of Points* with pressing or and then press .

Now you can select number of ignition points, with pressing or and then press .

5.2. Change PARAMETERS OF IGNITION CURVE POINT

Move to point you want to change, with pressing or and then press .

Now you can change rev point with pressing or (in 100 rpm steps) and then press .

Now you can change advance angle with pressing or (in 0.1deg steps) and then press .

6. Set ADVANCE

With this setting is possible to advance or retard whole ignition curve. When setting is positive then ignition curve is advanced and when setting is negative than ignition curve is retarded. With *Advance 0.0deg*, ignition curve is unchanged.

Enter menu and move to *Advance* with pressing or and then press .

Now you can set advance with pressing or (in 0.1deg steps) and then press .

7. Set SHIFT LIGHT

Enter menu and move to *Shift Light* with pressing or and then press .

Now you can change rev point with pressing or (in 100 rpm steps) and then press .

8. Set SHIFT KILL TIME

Enter menu and move to *Shift Kill Time* with pressing or and then press .

Now you can change kill time with pressing or (in 10 ms steps) and then press .

9. Set REV LIMIT

Enter menu and move to *Rev Limit* with pressing or and then press .

Now you can change rev limit with pressing or (in 100 rpm steps) and then press .

10. Set STATIC ANGLE

Enter menu and move to *Static Angle* with pressing or and then press .
Now you can set static angle with pressing or (in 0.1deg steps) and then press .
More information's about static angle you can find in section 22.

11. Set COMPENSATION

It is compensation of signal delay from pickup to spark plugs. You can check this delay with stroboscope lamp. Without this compensation, ignition advance angle decreasing with rising revs.

This compensation helps that advance angles in ignition curve are real (more accurate).

How to check, if compensation is correct:

First you must set flat ignition curve. Then measure with stroboscope lamp, if mark at flywheel moving when changing revs. If mark moving, then you must change compensation delay.

Change Compensation:

Enter menu and move to *Compensation* with pressing or and then press .
Now you can change compensation delay with pressing or and then press .

12. Set REMOTE SW

Enabling or disabling external switch for changing ignition curves while riding.

Enter menu and move to *Remote SW* with pressing or and then press .
Now you can enable or disable external switch with pressing or and then press .

13. Open Rev Point

Enter menu and move to *Open Rev Point* with pressing or and then press .
Now you can select revolutions for opening valve servo, with pressing or and then press .

14. Close Rev Point

Enter menu and move to *Close Rev Point* with pressing or and then press .
Now you can select revolutions for closing valve servo, with pressing or and then press .

15. Max Close Position

Enter menu and move to **Close Position** with pressing or and then press .

Now you can set close position with pressing or and then press .

Max close position is when curve is set to 0%. This close position can be moved to any desired position. For RZ350 default close position is 240. Max close position can be moved to deeply closed or less closed position.

16. Max Open Position

Enter menu and move to **Open Position** with pressing or and then press .

Now you can set open position with pressing or and then press .

Max open position is when curve is set to 100%. This open position can be moved to any desired position. For RZ350 default open position is 512. Max open position can be moved to more open or less open position.

17. PV Test

Enter menu and move to **PV Test** with pressing or and then press .

Now you can set valve position with pressing or and then press .

PV test can be used for testing or measuring valve position. Valve can be moved to any position from 0% to 100%, without engine running.

18. Power-up Test

Enabling or disabling power-up PV test.

Enter menu and move to **Power-up Test** with pressing or and then press .

Now you can enable or disable external switch with pressing or and then press .

19. MECHANICAL SETTINGS (Static Angle)

Static Angle is ignition advance angle, set with stator (generator). Measure this angle with dial gauge. This measured **Static Angle** is your maximum advance angle you can set with **PCDI**.

Example:

Measured Static Angle = 39.2deg (this angle you must enter in PCDI)

Calculating mm to deg or vice versa:

α = ignition advance in degrees

T = ignition advance in mm

R = engine stroke divided by 2 in mm

L = conrod length in mm

$P = R + L - T$

$$\alpha = \cos^{-1} \left(\frac{P^2 + R^2 - L^2}{2 \cdot P \cdot R} \right)$$

$$T = L + R \cdot (1 - \cos \alpha) - \sqrt{L^2 - (R \cdot \sin \alpha)^2}$$

20. MONITORING

Connect **programmer** to **PCDI** and wait few seconds for activation of **programmer**. First information displayed on the **programmer** is software version.

With **programmer** you can watch revs, calculated advance ignition angle and PV valve position.

Information!

You can connect or disconnect **PCDI** unit from **programmer** any time you want, without any harm. It is not important, if motor running or not and if power supply is connected or not.

Important!

Do not use too much force when connecting or disconnecting **programmer** unit!

21. ERROR REPORTS

Two errors can be displayed:

Program Memory Error - when program memory is corrupted. With this error present, function of program could be faulty.

EEPROM Error - when eeprom memory is corrupted. All programmable data are stored in eeprom memory (curve, rev limit...). With this error present, function of program could be faulty. *You must check all your settings and correct changed.*

PVerror 1 – position sensor error, or servo motor disconnected

PVerror 2 – servo motor error (short connection)