

updated 02.02.2016

program version: 00.140909

# USER MANUAL PDCI-24V PROGRAMMABLE CDI IGNITION AND PV CONTROLLER

#### **TECHNICAL DATA**

#### Limit values:

- minimum revs	200 RPM
- maximum revs	20000 RPM
- minimum supply voltage	7 Volts
- recommended power supply	12÷15 Volts
- maximum supply voltage	17 Volts
- stand-by current draw	< 0.09 Amp
- current draw at 1300 RPM	< 0.3 Amp
- current draw at 12000 RPM	< 1.7 Amp
- maximum continuous current for shift light and power jet output	1 Amp
- peak current for shift light and power jet output	5 Amp
- constant spark energy from idle to 13000 RPM	>35mJ

#### **Important!**

Avoid reverse power supply connection...circuit can handle reverse power supply only for short time.

#### Features:

- fast power-up (also starts only with condenser)
- full power starting spark energy already at 7Volts power supply
- one isolated input (pickup)
- two independent ignition coil outputs
- individual advance/retard of each output
- store and load function for two ignition maps
- external switch for changing ignition map while riding
- TPS input (Throttle Position Sensor)
- shift light output
- 2 power jet outputs
- duty cycle solenoid output (for regulating A/F ratio on some carburettors)
- quick shift (shift kill)
- soft rev limit (three stage rev limit)
- reduced spark at high revs with closed throttle (TCT mode)
- tachometer output
- easy and fast programming on the field, via hand held programmer
- programming while machine running you can immediately see effects
- each curve can be set in 4 to 12 curve points

- 3D interpolated ignition map, if TPS selected
- signal delay compensation
- instant monitoring of rev's and angle, via LCD(hand held programmer)
- programmable power valve actuation
- store and load function for 5 PV curves
- external switch for changing PV curve while riding
- programmable PV deviation
- programmable max close and max open positions
- self PV test on power-up
- PV error detecting (position sensor failure, servo motor failure)
- fast processing for high accuracy delays from 1us
- timing calculation for every 1 RPM change (1000, 1002, ..., 9805, 9806, ...)

### **Very important!**

Resistor spark plugs must be used, because they produce less electromagnetic disturbances.

# **Danger of electric shock!**

Avoid connecting PDCI to 12V power supply, before connecting it to ignition coil. High voltage is generated and touching free wires can cause electric shock, or damage the unit.

#### 1. HOW TO ENTER MENU

**PDCI** must be connected to power supply. Connect **programmer** to **PDCI** and wait few seconds for activation of **programmer** and then press enter. With pressing + or - you can move through menu and with pressing enter you can choose. You can exit menu with choosing *Exit*.

#### 2. MENU ORGANISATION

Set Ign. - set ignition parameters submenu Set PV - set PV parameters submenu

Exit

#### 2.1. SET IGNITION PARAMETERS SUBMENU

Load Ign. Map
- load (select) ignition map (from #1 to #2)
- save Ign. Map
- save new ignition map (from #1 to #2)
- ignition map parameters submenu

*Advance* - advance/retard whole ignition map on both ignition coil outputs

Advance 1 - advance/retard ignition coil output 1
 Advance 2 - advance/retard ignition coil output 2

Gear Shift Light - shift light

**Quick Shift** - quick shift settings

**Rev Limit** - rev limit

**Static Angle** - static angle (stator position)

**Compensation** - signal delay compensation (from pickup to spark plug)

**Power Jet 1** - power jet 1

Solenoid Output - solenoid output settings (power jet 2, or duty solenoid) - enable, or disable TPS **TPS TPS** close [0%] - calibrating TPS close position TPS open [100%] - calibrating TPS open position TCT mode - reduced spark at high revs with closed throttle Ign. Map SW - activating/deactivating external switch for selecting ignition map Pulses Per Rev - number pulses per revolution from pickup Exit 2.2. SET PV PARAMETERS SUBMENU Load PV Curve - load (select) PV curve (from #1 to #5) Save PV Curve - save new PV curve (from #1 to #5) Set PV Curve - PV curve parameters submenu - deviation of PV position Deviation +-- max close PV position Close Position **Open Position** - max open PV position - PV position test PV Test - enable, or disable test cycle at power-up Power-up Test PV Curve SW - activating/deactivating external switch for selecting PV curve Exit **3.** LOAD IGN. MAP Enter **Set Ign.** menu and move to **Load Ign. Map** with pressing |+| or |-| and then press | enter |. Now you can select number of saved ignition map, with pressing + or - and then press enter. 4. SAVE IGN. MAP Enter **Set Ign.** menu and move to **Save Ign. Map** with pressing |+| or |-| and then press | enter |. Now you can select number to which you want to save your ignition map, with pressing | + | or | and then press enter . 5. **SET IGNITION MAP** (if TPS disabled) Enter **Set Ign.** menu and move to **Set Ignition Map** with pressing + or - and then press enter. ...you entered submenu for setting ignition map. Submenu organisation: Nr. of Points - number of ignition curve points (from 4 to 12) - first ignition curve point *1*) *2*) - second ignition curve point

- exit submenu

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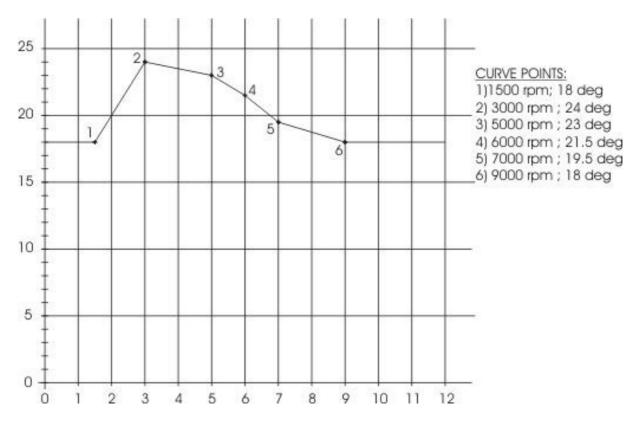
Exit

#### **Important!**

To avoid wrong processing, don't make unreasonable curve course.

Every time you make any changes to ignition curve, it is automatically saved to number #0. Later you can save it to any other number #1 or #2.

Curve Example with six curve points:



# **5.1. SET IGNITION MAP** (*if TPS enabled*)

Three ignition curves must be programmed for different TPS positions. **PDCI** does not only switch between ignition curves, but also interpolate 3D map for all TPS positions above 33%.

Enter *Set Ign*. menu and move to *Set Ignition Map* with pressing + or - and then press enter. ...you entered submenu for selecting ignition curve.

#### Submenu organisation:

*Nr. of Points* - number of ignition curve points (from 4 to 10)

*Curve 0-33*% - ignition curve from 0 to 33% TPS

Curve 66% - ignition curve for 66% TPS - ignition curve for 100% TPS

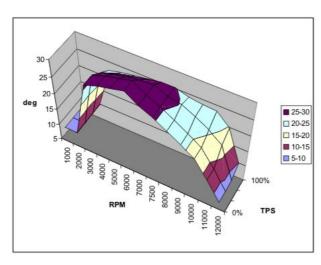
*Exit* - exit submenu

#### **Important!**

To avoid wrong processing, don't make unreasonable curve course.

Every time you make any changes to ignition curve, it is automatically saved to number #0. Later you can save it to any other number #1 or #2.

Ignition Map Example:



# **5.2.** Change NUMBER OF IGNITION CURVE POINTS

Move to *Nr. of Points* with pressing + or - and then press enter .

Now you can select number of ignition points, with pressing + or - and then press enter .

# **5.3.** Change PARAMETERS OF IGNITION CURVE POINT

Move to point you want to change, with pressing + or - and then press enter.

Now you can change rev point with pressing + or - (in 100 rpm steps) and then press enter.

Now you can change advance angle with pressing + or - (in 0.1deg steps) and then press enter.

#### 6. ADVANCE

With this setting is possible to advance, or retard whole ignition map on both ignition coil outputs. When setting is positive, then ignition map is advanced and when setting is negative, than ignition map is retarded. Ignition map is unchanged, with setting **0.0deg**.

Enter menu and move to *Advance*, with pressing + or - and then press enter.

Now you can set advance with pressing + or - (in 0.1deg steps) and then press enter.

# 7. ADVANCE 1

With this setting is possible to advance, or retard ignition map only on ignition coil output 1. When setting is positive, then ignition map is advanced and when setting is negative than, ignition map is retarded. Ignition map is unchanged, with setting <i>0.0deg</i> .
Enter menu and move to <i>Advance</i> , with pressing + or - and then press enter.  Now you can set advance with pressing + or - (in 0.1deg steps) and then press enter.
8. ADVANCE 2
With this setting is possible to advance, or retard ignition map only on ignition coil output 2. When setting is positive then, ignition map is advanced and when setting is negative than, ignition map is retarded. Ignition map is unchanged, with setting <i>0.0deg</i> .
Enter menu and move to <i>Advance</i> , with pressing + or - and then press enter.  Now you can set advance with pressing + or - (in 0.1deg steps) and then press enter.
9. GEAR SHIFT LIGHT
Enter <b>Set Ign.</b> menu and move to <b>Gear Shift Light</b> with pressing + or - and then press enter Now you can change rev point with pressing + or - (in 100 rpm steps) and then press enter
10. QUICK SHIFT
Enter <b>Set Ign.</b> menu and move to <b>Quick Shift</b> with pressing + or - and then press enteryou entered submenu for quick shift settings.
Submenu organisation:  Shift Kill Time - basic kill time  Smart Shift - activating/deactivating automatic kill time for different revs  Exit - exit submenu
10.1. SHIFT KILL TIME
Enter <i>Quich Shift</i> menu and move to <i>Shift Kill Time</i> with pressing + or - and then pressenter.  Now you can change kill time with pressing + or - (in 10 ms steps) and then pressenter.

# 10.2. SMART SHIFT

Smart shift function automatically adjusts kill time for different revs. Shift kill time must be always set, as basic kill time.		
Enter <i>Quich Shift</i> menu and move to <i>Smart Shift</i> with pressing + or - and then press enter.  Now you can enable, or disable function with pressing + or - and then press enter.		
11. REV LIMIT		
Enter <i>Set Ign</i> . menu and move to <i>Rev Limit</i> with pressing + or - and then press enter.  Now you can change rev limit with pressing + or - (in 100 rpm steps) and then press enter.		
12. STATIC ANGLE		
Enter <i>Set Ign</i> . menu and move to <i>Static Angle</i> with pressing + or - and then press enter. Now you can set static angle with pressing + or - (in 0.1deg steps) and then press enter.		
More information's about static angle you can find in section 31.		
13. COMPENSATION		
It is compensation of signal delay from pickup to spark plugs. You can check this delay with stroboscope lamp. Without this compensation, ignition advance angle decreasing with rising revs.		
This compensation helps that advance angles in ignition curve are real (more accurate).		
How to check, if compensation is correct: First you must set flat ignition curve. Then measure with stroboscope lamp, if mark at flywheel moving when changing revs. If mark moving then you must change compensation delay.		
Change Compensation: Enter menu and move to <i>Compensation</i> with pressing + or - and then press enter.  Now you can change compensation delay with pressing + or - and then press enter.		
14. POWER JET 1		
Enter <i>Set Ign</i> . menu and move to <i>Power Jet 1</i> with pressing + or - and then press enteryou entered submenu for setting <i>Power Jet 1</i> parameters.		
Submenu organisation:		
Power Jet 1 ON RPM - revs for activating power jet 1 Power Jet 1 OFF RPM - revs for deactivating power jet 1		
Power Jet 1 ON TPS (if TPS enabled) - throttle position for activating power jet 1		
Power Jet 1 OFF TPS (if TPS enabled) - throttle position for deactivating power jet 1 - exit submenu		

Example:  Power jet 1 $ON(RPM) = 8000rpm$ Power jet 1 $OFF(RPM) = 10000rpm$ Power jet 1 $ON(TPS) = 70\%TPS$ power jet 1 $OFF(TPS) = 90\%TPS$
Power jet is switched on when revs are between 8000-10000rpm and throttle position is between 70-90%, otherwise power jet is switched off.
14.1. POWER JET 1 ON RPM
Enter <b>Set Ign.</b> menu and move to <b>Power Jet 1 ON RPM</b> with pressing + or - and then press enter.
Now you can change <i>Power Jet 1 ON RPM</i> with pressing + or - (in 100 rpm steps) and then press enter.
14.2. POWER JET 1 OFF RPM
Enter <i>Set Ign</i> . menu and move to <i>Power Jet 1 OFF RPM</i> with pressing + or - and then press enter.
Now you can change <i>Power Jet 1 OFF RPM</i> with pressing + or - (in 100 rpm steps) and then press enter.
14.3. POWER JET 1 ON TPS (if TPS enabled)
Enter <b>Set Ign.</b> menu and move to <b>Power Jet 1 ON TPS</b> with pressing + or - and then press
Now you can change TPS position with pressing + or - (in 1%TPS steps) and then pressenter.
14.4. POWER JET 1 OFF TPS (if TPS enabled)
Enter Set Ign. menu and move to Power Jet 1 OFF TPS with pressing + or - and then press

Now you can change TPS position with pressing + or - (in 1%TPS steps) and then press

enter .

# 15. SOLENOID OUTPUT

Enter <i>Set Ign</i> . menu and move to <i>Solenoid</i> you entered submenu for setting <i>Solenoid</i>	<i>Output</i> with pressing + or - and then press enter <i>Output</i> parameters.
Submenu organisation:	
Output type	- select output type (Power Jet 2, or Duty Solenoid)
Power Jet 2 (if selected)  Duty Selected (if selected)	- set Power Jet 2 parameters
Duty Solenoid (if selected) Exit	<ul><li>set Duty Solenoid parameters</li><li>exit submenu</li></ul>
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15.1. OUTPUT TYPE	
Solenoid output function can be configured used for adjusting A/F ratio on some carbu	as Power Jet 2, or Duty Solenoid. Duty solenoid is rettors.
Enter <b>Solenoid Output.</b> menu and move to enter.	Output type with pressing + or - and then press
	with pressing + or - and then press enter.
15.2. POWER JET 2 (if selected in Outp	out Type menu)
Same settings as <i>Power Jet 1</i> look at section	on 14.
15.3. DUTY SOLENOID (if selected in	Output Type menu)
Three duty cycle curves for different throttle programmed in 8 rev points.	le positions can be programmed. Each curve can be
Enter <b>Solenoid Output</b> menu and move to benter.	Duty Solenoid with pressing + or - and then press
you enterd submenu for setting <i>Duty Sole</i>	enoid parameters.
Submenu organisation:	
Curve 0-33% - duty cycle curve from	om 0 to 33% TPS
Curve 34-66% - duty cycle curve from	
Curve 67-100% - duty cycle curve from	om 67 to 100% TPS
<i>Exit</i> - exit submenu	
15.3.1 Set PARAMETERS FOR DUTY	SOLENOID CURVE POINT
Move to point you want to change, with pro-	
	ing + or - (in 100 rpm steps) and then press enter.  ing + or - (in 1% steps) and then press enter.

16.	TPS
Enabli	ng, or disabling Throttle Position Sensor.
	Set Ign. menu and move to TPS with pressing + or - and then press enter.  you can enable or disable TPS with pressing + or - and then press enter.
17.	Set TPS close [0%] (if TPS enabled)
Enter S Leave	rect operation, TPS close position must be calibrated!  Set Ign. menu and move to TPS close [0%] with pressing + or - and then press enter. throttle at close position and confirm calibrating with pressing enter, or exit calibration ressing Displayed number should be between 0 and 500.
18.	Set TPS open [100%] (if TPS enabled)
Enter S Move	rect operation, TPS open position must be calibrated!  Set Ign. menu and move to TPS open [100%] with pressing + or - and then press enter throttle to maximum open position and confirm calibrating with pressing enter , or exit ation with pressing - Displayed number should be between 500 and 1010.
19.	TCT mode
	le Close spark Termination mode, reduces number of sparks (spark is active every third tion) above 8000rpm, when throttle is closed. TCT mode ensure better engine cooling.
	Set Ign. menu and move to TCT mode with pressing + or - and then press enter.  you can enable or disable TCT mode with pressing + or - and then press enter.
20.	IGN. MAP SW
Enabli	ing, or disabling ignition map switch, for changing ignition maps while riding.
	Set Ign. menu and move to Ign. Map SW with pressing + or - and then press enter.  you can enable or disable external switch with pressing + or - and then press enter.

# 21. PULSES PER REV

It is number of pulses per rev from pickup coil and is important for correct rev reading. Setting is 2 for all twins with wasted spark ignition system.

Enter *Set Ign.* menu and move to *Pulses Per Rev* with pressing + or - and then press enter.

Now you can change nr. of pulses per rev with pressing + or - and then press enter.

# 22. LOAD PV CURVE

Enter <i>Set PV</i> menu and move to <i>Load PV Curve</i> with pressing + or - and then press enter.  Now you can select number of PV curve with pressing + or - and then press enter.				
23. SAVE PV C	URVE			
Enter <i>Set PV</i> menu and move to <i>Save PV Curve</i> with pressing + or - and then press enter.  Now you can select number to save your PV curve, with pressing + or - and then press enter.				
24. Set PV Curv	e			
Enter <i>Set PV</i> menu and move to <i>Set PV Curve</i> with pressing + or - and then press enteryou entered submenu for setting PV curve.				
Submenu organisation Nr. of Points  1) 2)	on: - number of PV curve points (from 2 to 8) - first valve position point - second valve position point			
Exit	exit submenu			
Important!  To avoid wrong processing, don't make unreasonable curve course.  Every time you make any changes to PV curve, it is automatically saved to number #0. Later you can save it to any other number from #1 to #5.				
24.1. Change Num	nber of Curve Points			
Move to <i>Nr. of Points</i> with pressing + or - and then press enter.  Now you can select number of curve points, with pressing + or - and then press enter.				
24.2. Change Para	ameters of PV Curve Points			
Move to point you want to change, with pressing + or - and then press enter.  Now you can change rev point with pressing + or - (in 100 rpm steps) and then press enter.  Now you can change PV position from 0% to 100%, with pressing + or - (in 1% steps) and then press enter.				

25. Set Deviation
Enter <i>Set PV</i> menu and move to <i>Deviation</i> with pressing + or - and then press enter. Now you can change deviation from 2% to 20% with pressing + or - (in 1% steps) and then press enter.  Deviation means how accurate valve is moved to calculated position. If deviation is too low then servo motor won't be stabile – it will always search for calculated position in small movements. Default setting is +-5% and should meet in most cases.
26. CLOSE POSITION
Max close position must be calibrated after installation. Max close position is when curve is set to 0%. Close position can be moved to any desired position.
Enter <i>Set PV</i> menu and move to <i>Close Position</i> with pressing + or - and then press enter. Now you can set close position with pressing + or - and then press enter.
27. OPEN POSITION
Max open position must be calibrated after installation. Max open position is when curve is set to 100%. Open position can be moved to any desired position.
Enter $Set\ PV$ menu and move to $Open\ Position$ with pressing $+$ or $-$ and then press enter. Now you can set open position with pressing $+$ or $-$ and then press enter. Max open position is when curve is set to $100\%$ . This open position can be moved to any desired position.
28. PV Test
PV test can be used for testing or measuring valve position. Valve can be moved to any position from $0\%$ to $100\%$ , without engine running.
Enter <i>Set PV</i> menu and move to <i>PV Test</i> with pressing + or - and then press enter. Now you can set valve position with pressing + or - and then press enter.
29. POWER-UP Test
Enabling or disabling test cycle of PV servo at power-up.

Enter *Set PV* menu and move to *Power-up Test* with pressing + or - and then press enter. Now you can enable or disable power-up test with pressing + or - and then press enter.

#### 30. PV CURVE SW

Enabling, or disabling PV curve switch for changing PV curves while riding.

Enter *Set PV* menu and move to *PV Curve SW* with pressing + or - and then press enter. Now you can enable, or disable *PV Curve* switch with pressing + or - and then press enter.

# 31. MECHANICAL SETTINGS (Static Angle)

**Static Angle** is ignition advance angle, set with stator (generator). Measure this angle with dial gauge. This measured **Static Angle** is your maximum advance angle you can set with **PDCI**.

Calculating mm to deg or vice versa:

 $\alpha$  = ignition advance in degrees T = ignition advance in mm R = engine stroke divided by 2 in mm L = conrod length in mm P = R + L - T  $\alpha = \cos^{-1} \left( \frac{P^2 + R^2 - L^2}{2 \cdot P \cdot R} \right)$   $T = L + R \cdot (1 - \cos \alpha) - \sqrt{L^2 - (R \cdot \sin \alpha)^2}$ 

### 32. MONITORING

Connect **programmer** to **PDCI** and wait few seconds for activation of **programmer**. Fist information displayed on the **programmer** is software version.

With **programmer** you can watch revs, calculated advance ignition angle, TPS position...depends on setting in the menu.

# **Information!**

You can connect or disconnect **PDCI** unit from **programmer** any time you want, without any harm. It is not important, if motor running or not and if power supply is connected or not.

# **Important!**

Do not use too much force when connecting or disconnecting **programmer** unit!

#### 33. ERROR REPORTS

**PVerr 1** – position sensor error or servo motor disconnected

**PVerr 2 –** servo motor error (short connection)